

Working Together on Current Advantages and Future Possibilities

Using examples from CARIS 2014

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CARIS 2014

Brest France, June 2-5, 2014

Boot Camps

User Group Meetings

Technical and Non-technical Papers

Poster Sessions

Industry Exhibition Areas

CARIS 2014

CARIS Users (and others) from around the world

E.g.:

Mapping Agencies and Hydrographic offices

Port Authorities and Waterway Authorities

Academic Institutions and Students

Hardware Manufacturers and Service Providers

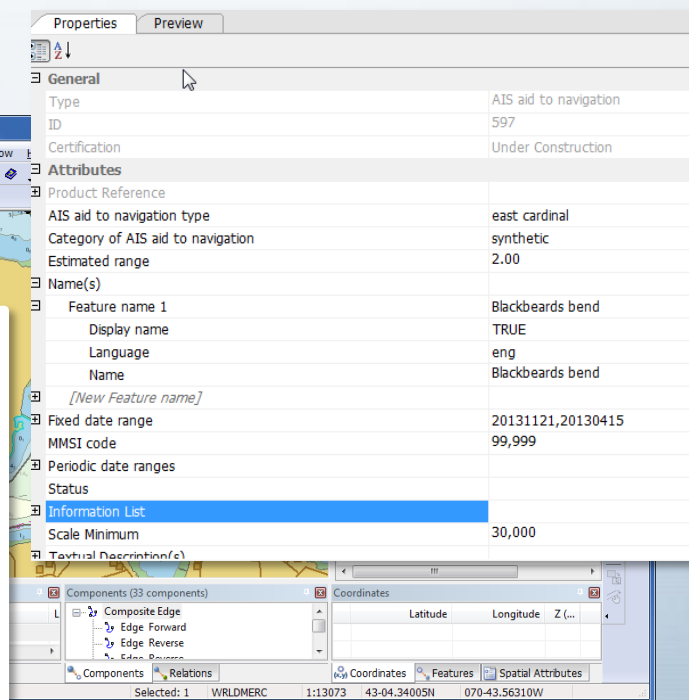
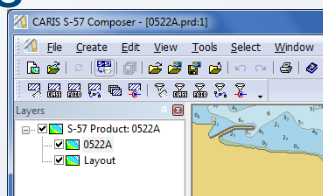
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Sponsors and Exhibitors

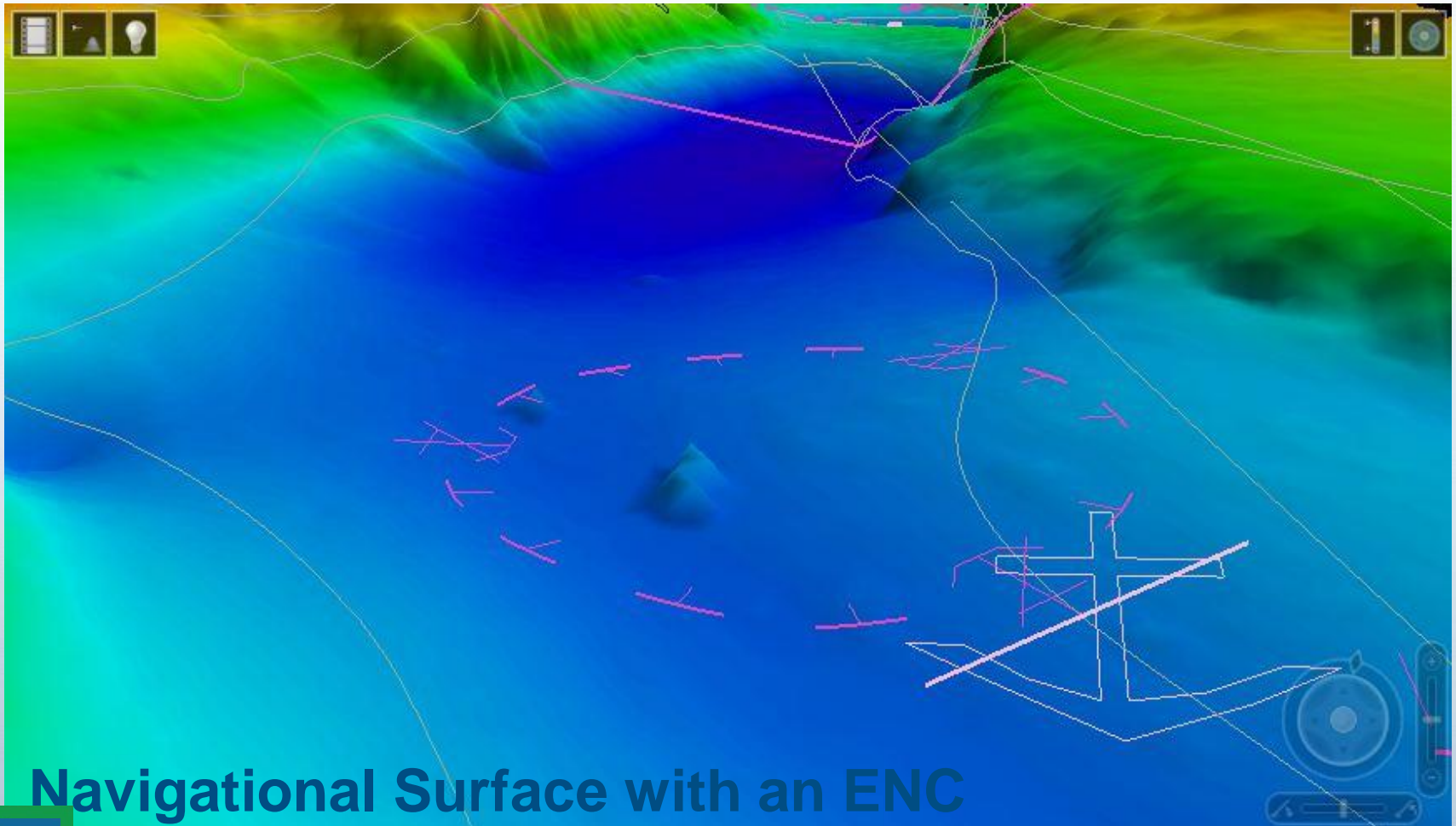


S-100 Boot Camp

- Theory
- S-102 & S-101 production
- S-57 to S-101 (and vice versa)
- Future S-1000 products
- Etc.



S-102 with S-57/S-101



Navigational Surface with an ENC

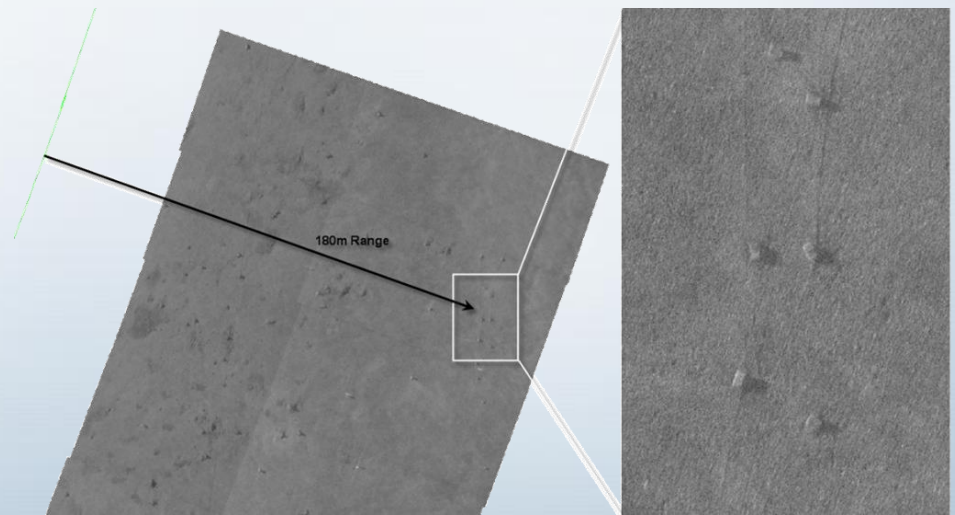
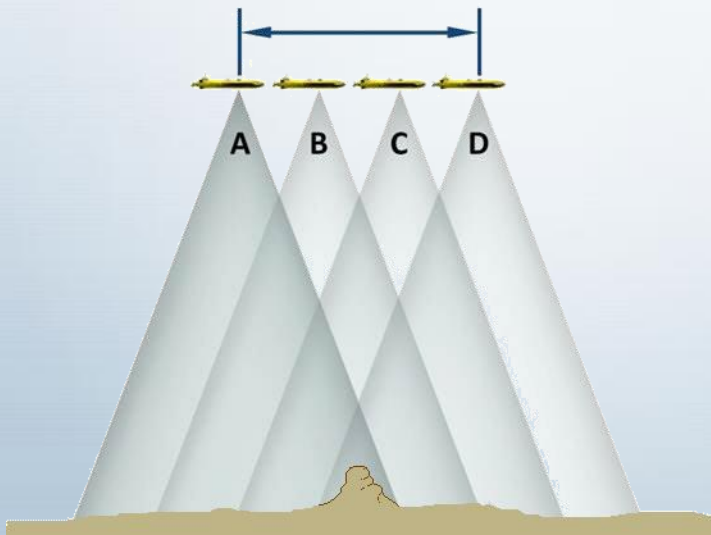
S-102

- Being used
 - E.g. for survey contract delivery
- But work on the standard is needed
 - CARIS has reported issues to IHO



Synthetic Aperture Sonar (SAS)

- High resolution images and bathymetry
- Requires stable vehicle
 - E.g. Autonomous Underwater Vehicle (AUV)



Synthetic Aperture Sonar (SAS)

Why Synthetic Aperture Sonar?

Ultra High Image Resolution

- Constant along/across track resolution of 3cm x 3cm
- 25x better compared to SSS

Increased Area Coverage Rate

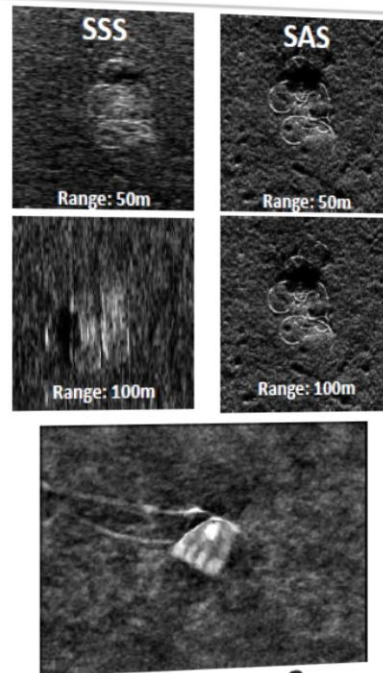
- Up to 600m swath
- 10x better compared to SSS

Operational Safety

- Ability to fly under ice at greater stand-off distances

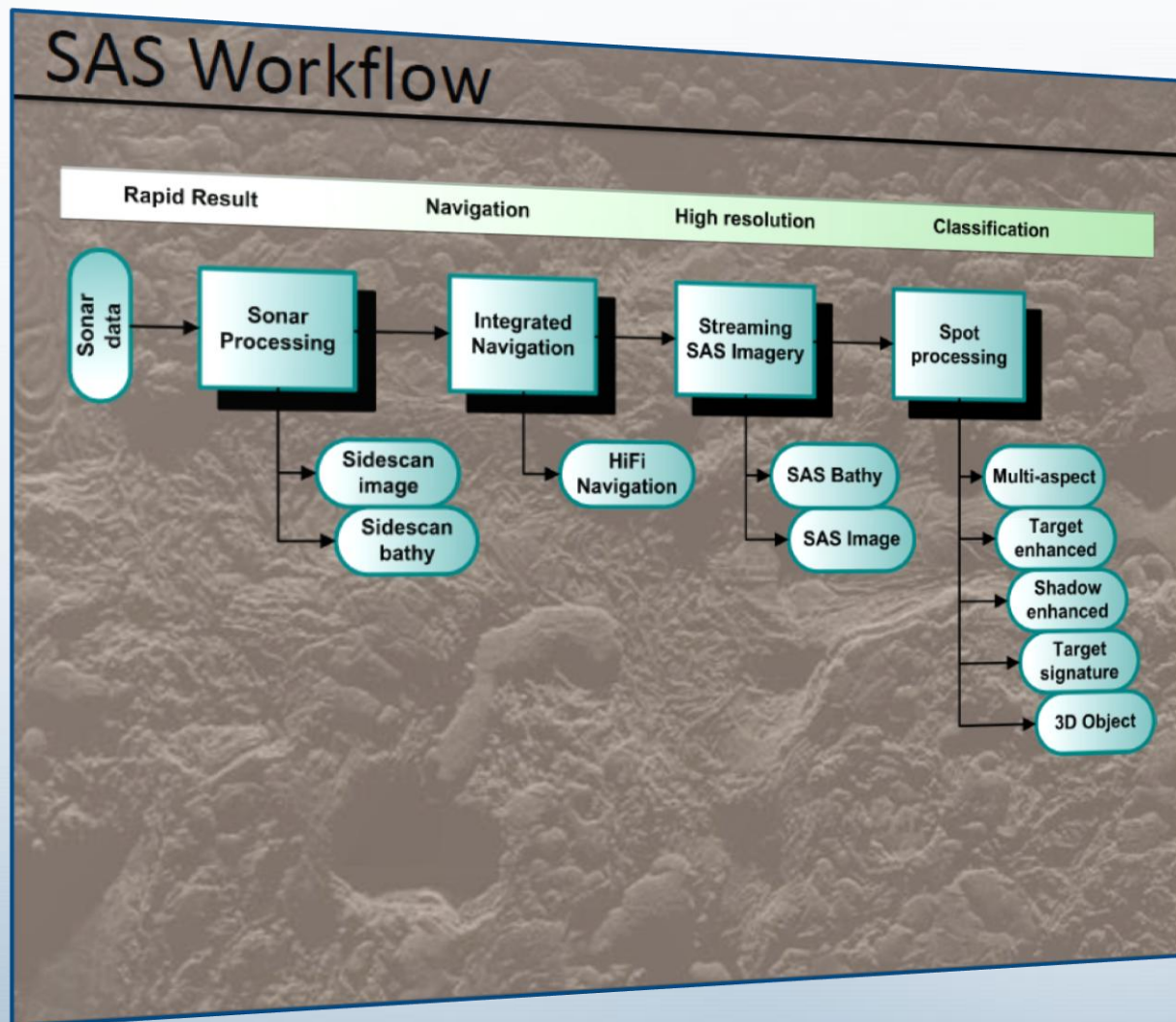
Additional By-Products

- Real-time, co-registered high resolution 3D bathymetry
- Rapid Environmental Assessment via data fusion
- Multi-aspect SAS can create optical-like quality imagery
- Shadow enhancement improves target classification
- Enhances AUV micronavigation capabilities



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Synthetic Aperture Sonar (SAS)

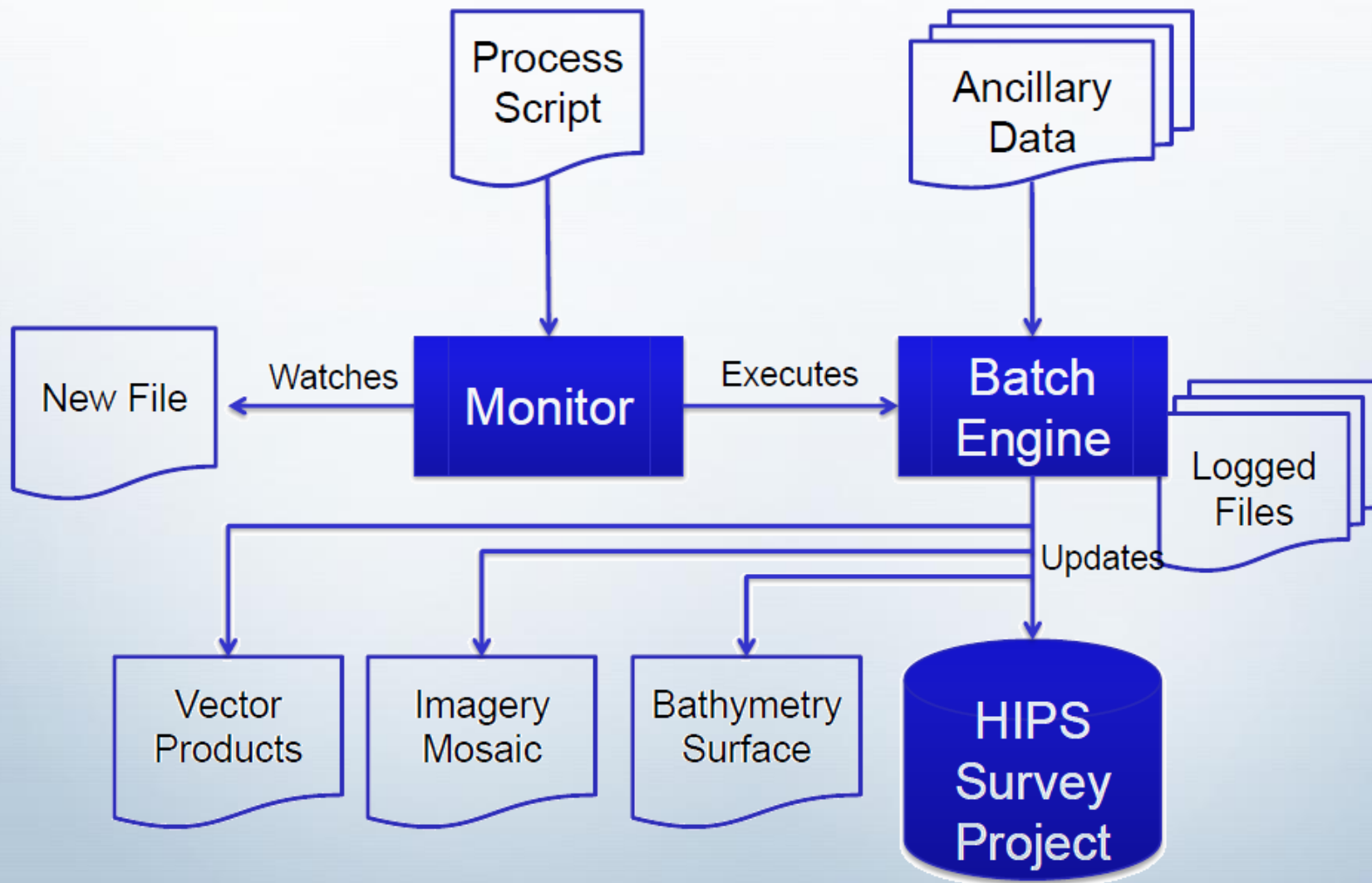


University of Bergen: Alden R. Denny, Rolf B. Pedersen
FFI: Roy E. Hansen, Torstein O. Sæbø

Unmanned (Undersea) Vehicles

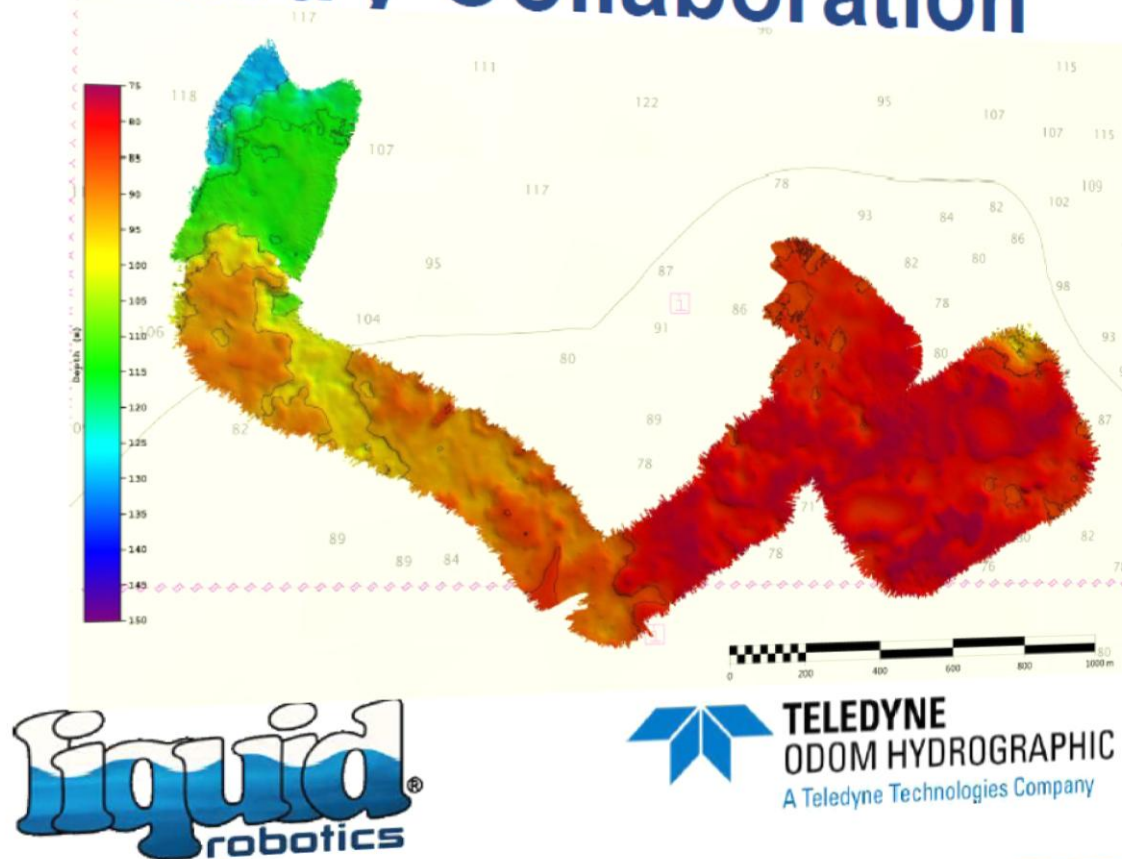


CARIS OnBoard



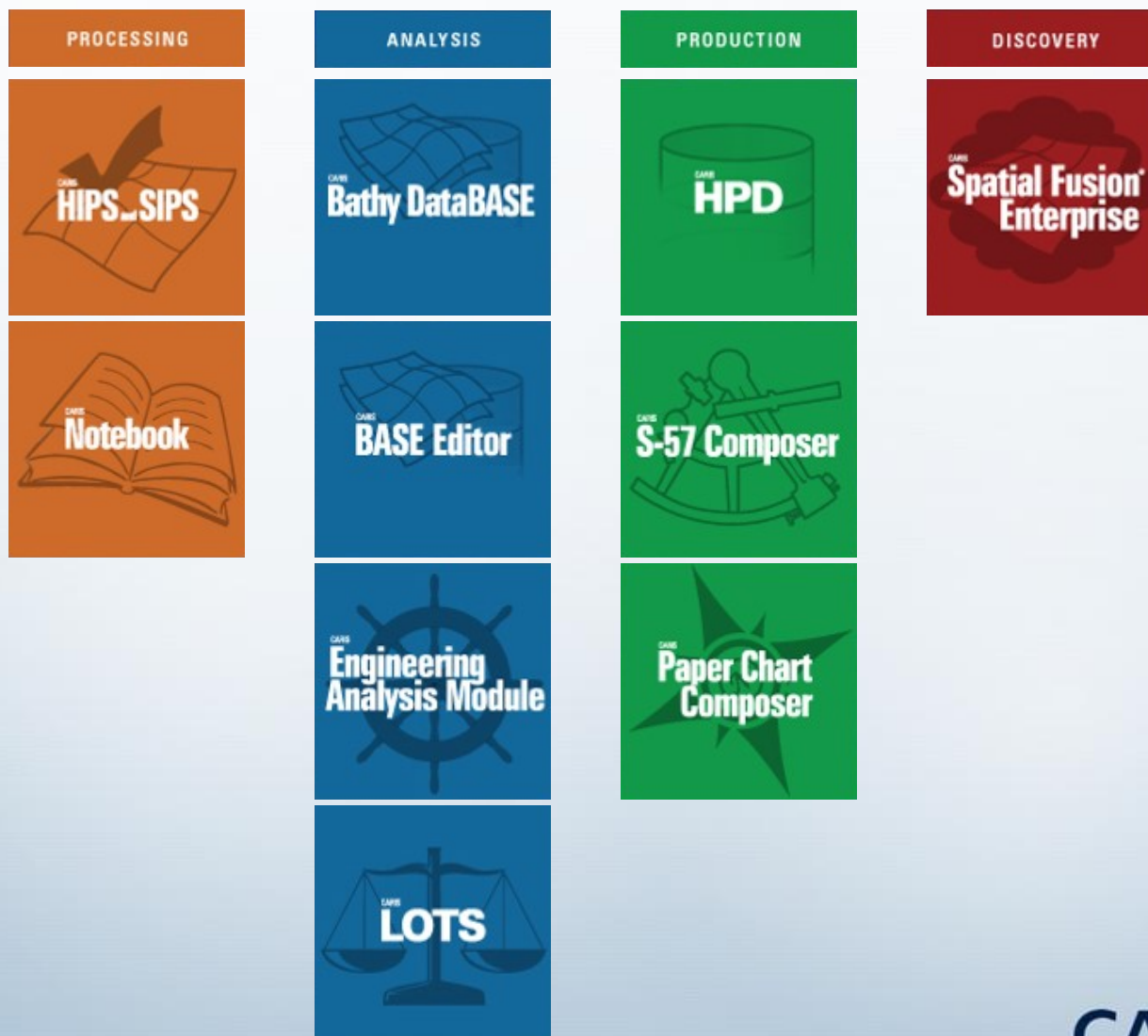
CARIS OnBoard

Industry Collaboration



CARIS: Bill Lamey

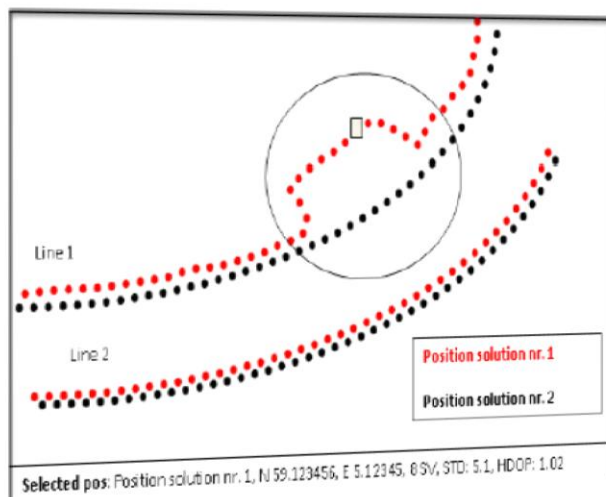
CARIS Ping-to-Chart



Bathymetric Processing

Different positioning systems

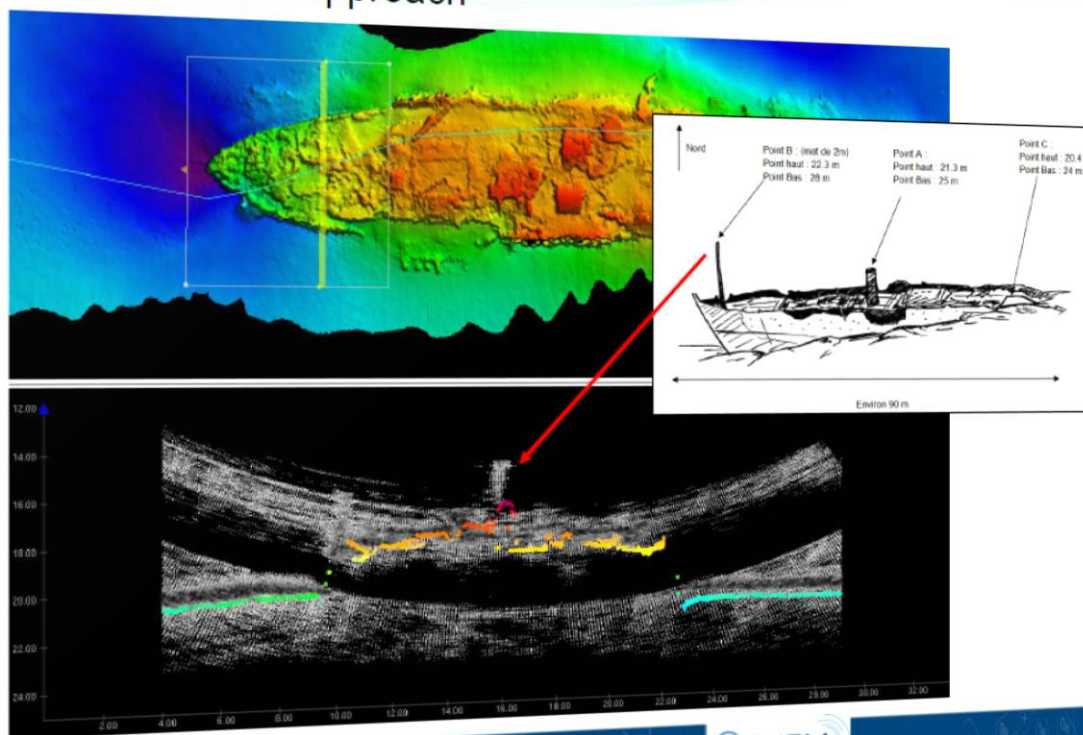
NHS use different navigation systems during surveying.
Tool to select best positions for the survey lines (drop B, aug. 2014)



- Geographically view of
 - > Post processed positions
 - > Real time solutions
- Set primary position solution whole survey
- Set another position solution for selected lines

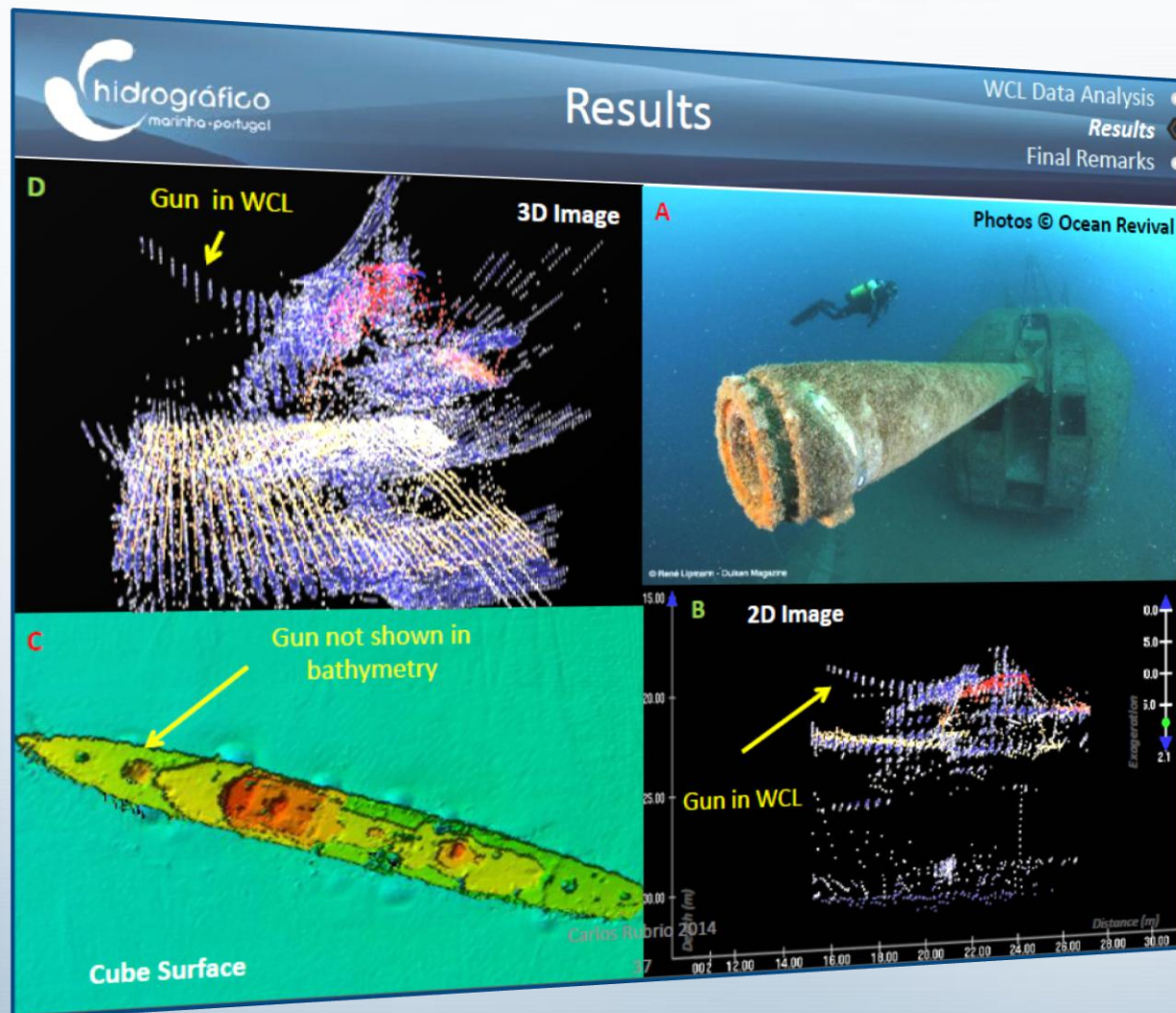
Water Column Imagery

Water Column : first approach



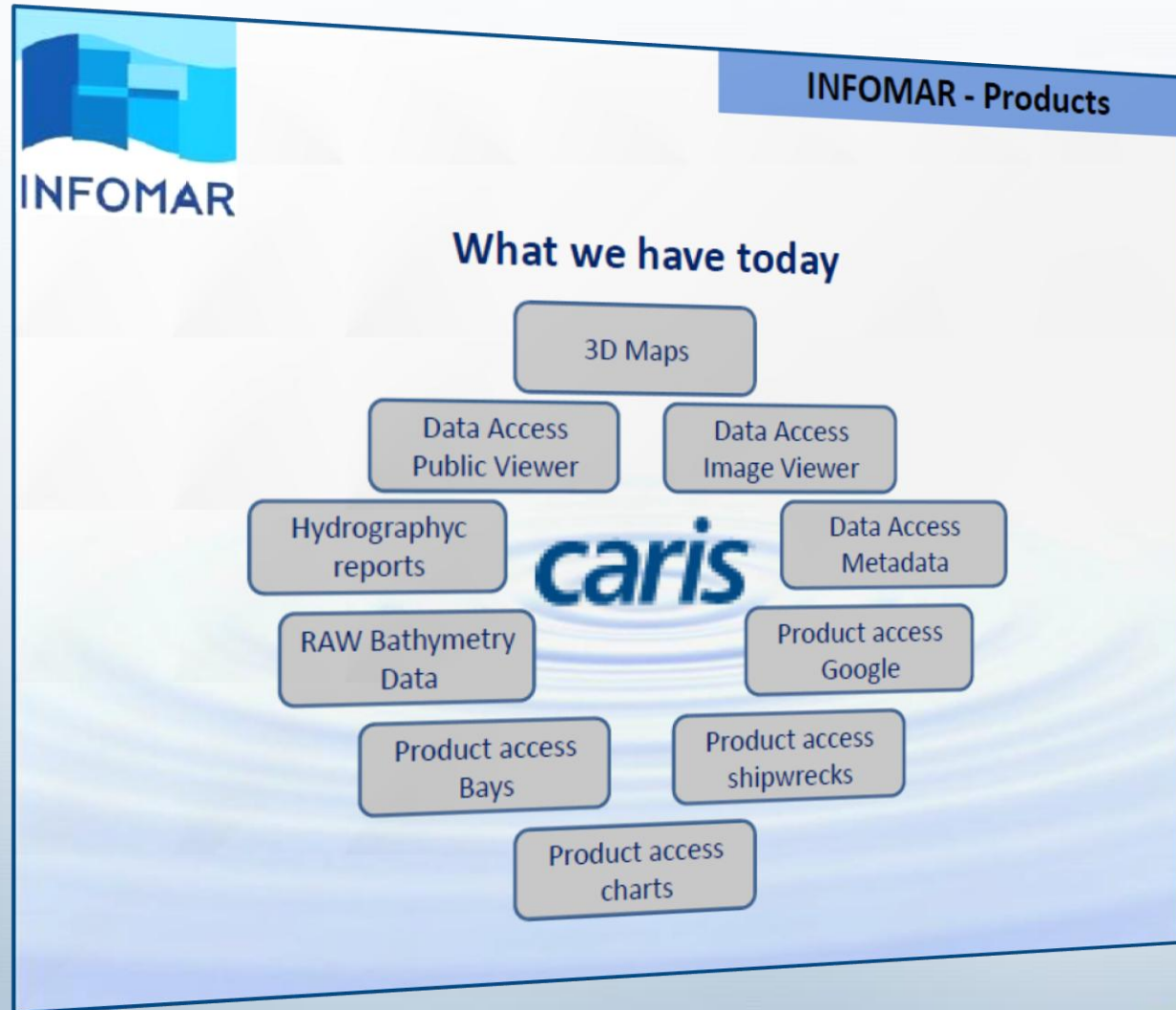
SHOM: Christophe Vignaud, Sophie Loyer,
Thierry Schmitt, Ronan Leroy

Water Column Imagery

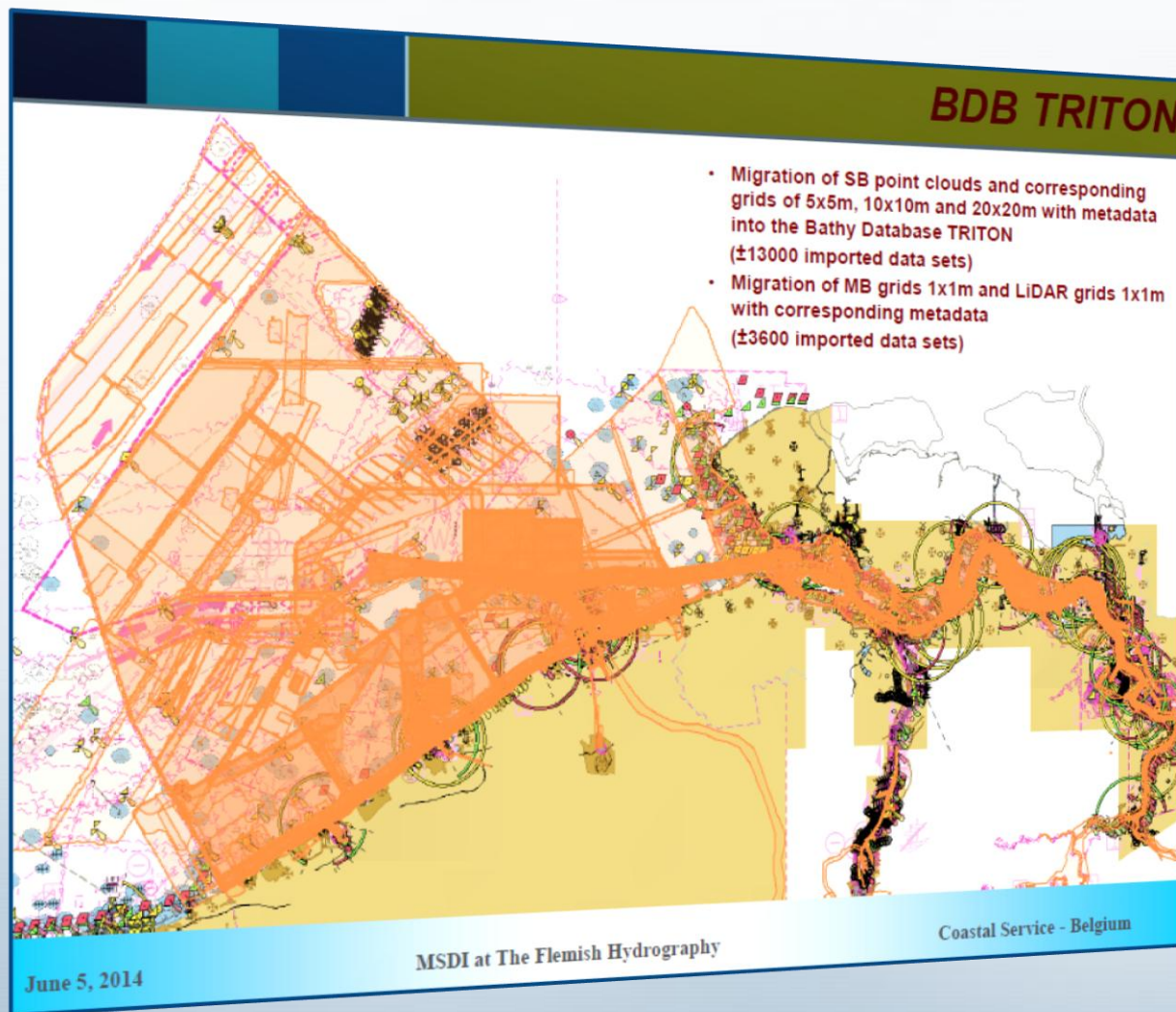


Portuguese HO: Carlos Rúbrio Marques

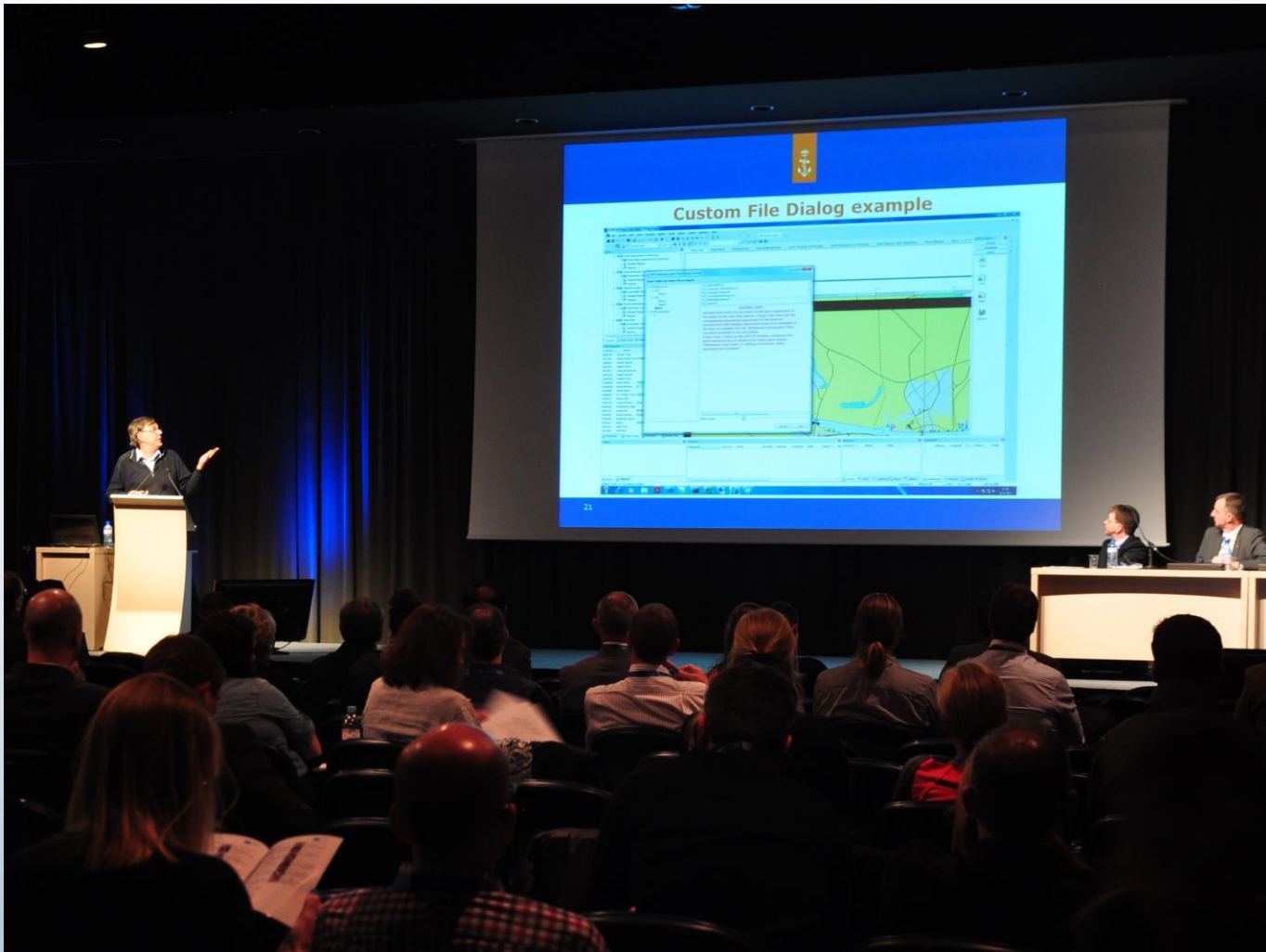
Data Utilization



Survey Management & Analysis



Integrating systems



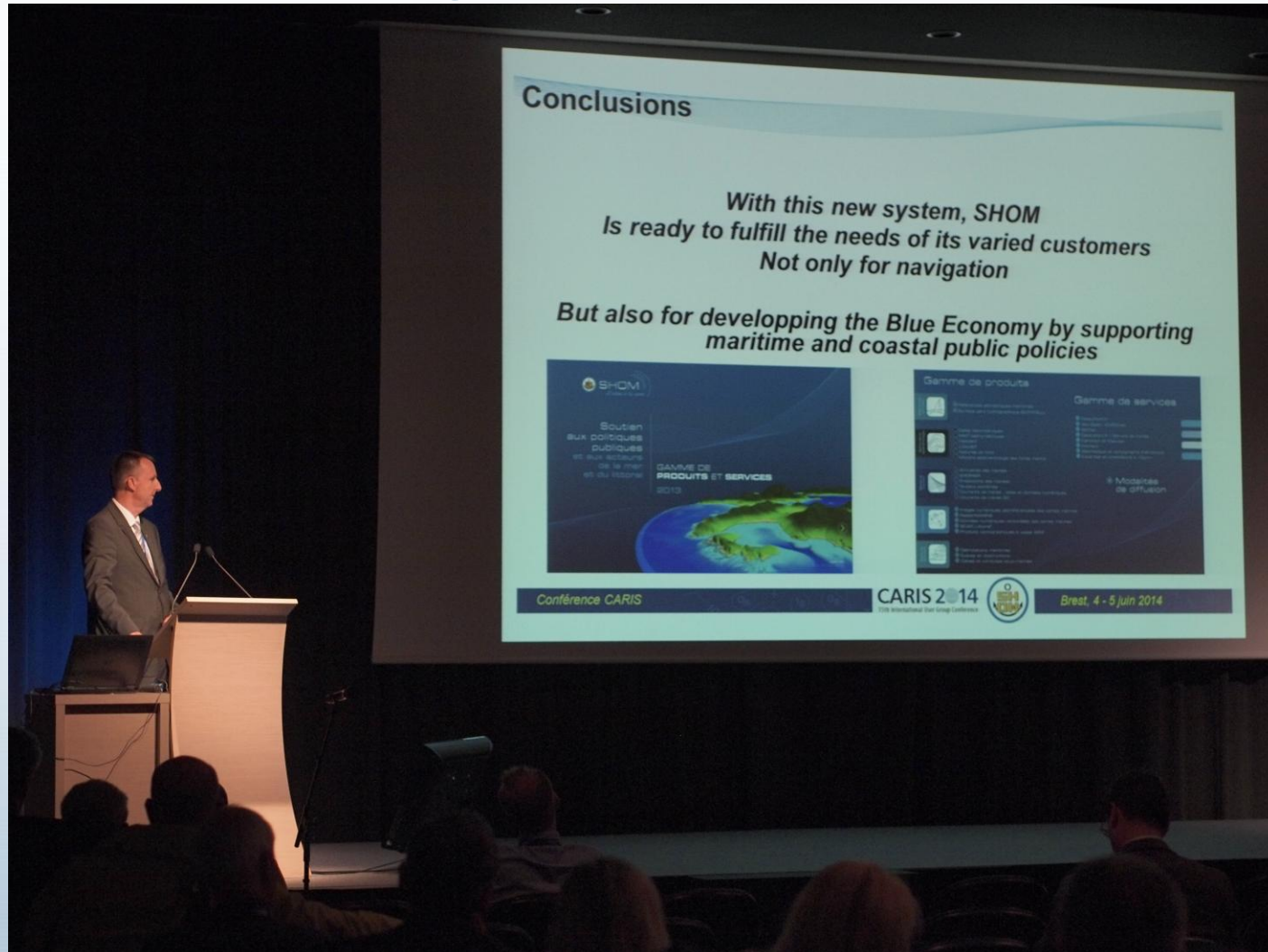
Netherlands Hydrographic Service: René van Geesbergen

Data Management & Production



UKHO: James Carey, Simon Matthews

Data Management & Production



SHOM: Eric LeGuen



CSAR Raster in FME 2014 s
CSAR Point Cloud in FME 2



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