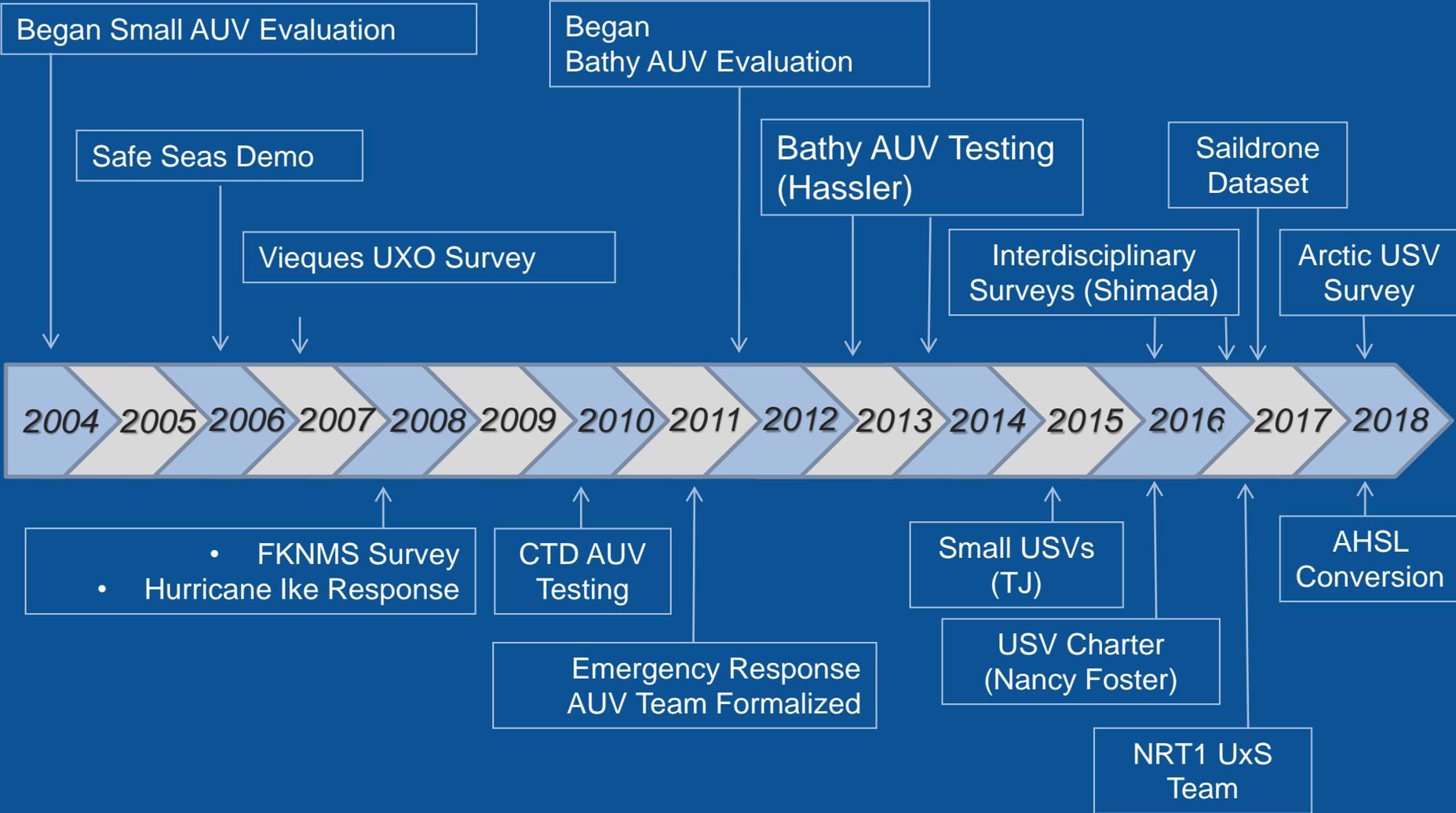


# Overview of Coast Survey's Unmanned System Activities & Strategy



# Coast Survey's Unmanned Systems Experience



# Coast Survey's Unmanned Systems In Operation or Evaluated

## Currently Owned Systems (Located with NRT1 – Stennis, MS)



Hydroid REMUS-100



Hydroid REMUS-600



Teledyne Oceanscience Z-Boat (2)



Seafloor Systems Echoboat (2)

## Previously Owned Systems



VCT Harborscan (Retired)



OceanServer Iver (Transferred)



REMUS-600 (Lost)

## Collaborative Systems



ASV C-Worker 4  
(UNH CCOM/JHC)



ASV C-Worker 5  
(USM)

## Multi-Use Systems



Optionally-manned Survey Launch  
(NOAA Ship *Rainier*)



# Shipboard USV Demonstrations

## Habitat Mapping on *Nancy Foster* – 2016

- Chartered ASV Global C-Worker 5
- Collaboration with NCCOS
- Coordinated surveys with the ship to explore operational concepts and shipboard requirements



## Arctic USV Survey – July 2018

- UNH's ASV C-Worker 4
- Collaboration with UNH CCOM/JHC, NOAA Ship *Fairweather*
- Tested new operational models, identified and solved technical shortcomings, and provided experience to the ship's crew in the operations and support of unmanned systems.

# Recent Activities – Optionally Manned Survey Launch

## Purpose

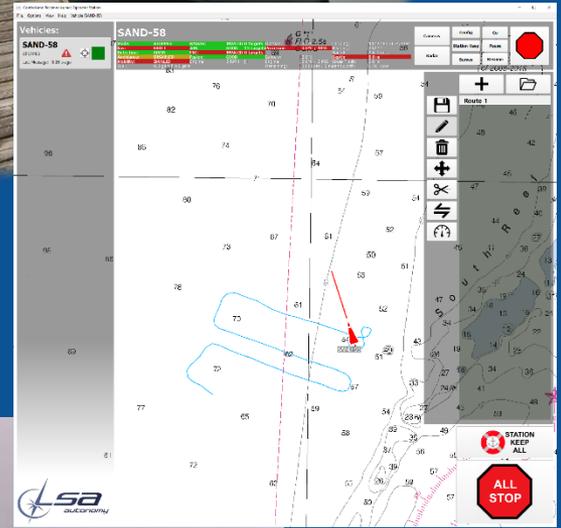
- Maximize current infrastructure and expertise
- Allow for expedited, moderately priced, and scalable means to integrate unmanned systems

## Expected Benefits

- Platform to develop and test enabling technologies & operational concepts
- More effective use of survey personnel
- Increased survey efficiency

## Status

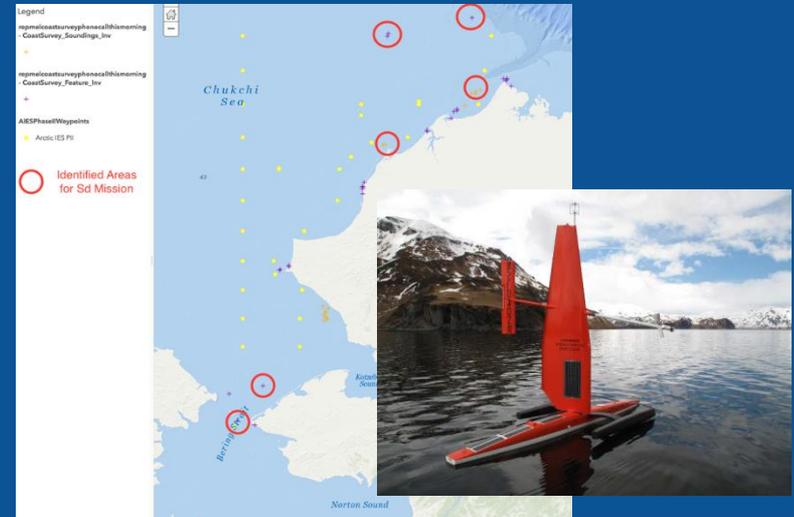
- Feb 2019 – Technical Acceptance of 1<sup>st</sup> launch conversion on NOAA Ship RAINIER
- Mar 2019 – Installation & Acceptance of 2<sup>nd</sup> launch conversion
- Spring/Summer 2019 – At-sea operational testing



# Collaborative Activities

## SailDrone

- Collaboration with NOAA PMEL
- Opportunistic mapping to support charting efforts
- Potential Missions – Reconnaissance, chart assessment, and investigation of chart discrepancies



## UNH iXBlue DriX ASV

- Testing and evaluation of the long endurance iXBlue DriX ASV through UNH's industrial partners program

## USM Sailandrone Research

- Testing and evaluation along the Gulf Coast to identify benefits to charting mission (cooperative agreement/grant)



# Key Lessons Learned

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- Unmanned systems require the development of **enabling technologies**, such as automated data processing and high-bandwidth communications, that can also benefit manned operations.
- Unmanned systems should provide **new capabilities**; one-for-one replacement of manned platforms in existing mission profiles is not effective.
- Unmanned systems require skilled **personnel** to operate and maintain, and do not necessarily reduce staffing requirements, but can allow for the more effective use of personnel.

# Key Lessons Learned

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- Unmanned systems do not diminish the need for **ships**, which may be necessary to deliver systems to remote locations and provide operational control and logistical support.
- Unmanned systems require unique shipboard and land-based **infrastructure**, including launch and recovery systems (LARS), maintenance facilities, and communications, for their safe and effective operation.
- Unmanned systems require **supervision** on a spectrum ranging from remote-controlled to fully autonomous depending on the environment and system capabilities.

*Develop and utilize unmanned systems for more efficient and effective acquisition of environmental data to support NOAA's navigation products and services.*

# Strategy

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**Develop Enabling Technologies** - Support the development and adoption enabling technologies to advance unmanned systems and benefit conventional manned operations.

**Maintain Operational Expertise** - Develop and maintain operational expertise with unmanned systems.

**Operational Innovation** - Support the development and transfer-to-operations of unmanned systems that benefit Coast Survey and NOAA missions.

**Collaborate** - Collaborate with government, academic, and industry partners to share expertise and resources and to direct and expedite system development.

# Strategy

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## ***Develop Enabling Technologies***

- **Activities** - Software Development (Charlene, TensorScan), Data Radio Evaluation
- **2019 Goal** - Reduce shipboard data processing effort 50% from 2017 level

## ***Maintain Operational Expertise***

- **Activities** – UxS Operational Team in Stennis
- **2019 Goal** – Team fully staffed and resourced to conduct Coast Survey and inter-disciplinary missions

## ***Operational Innovation***

- **Activities** – Optionally-manned Launch Conversions
- **2019 Goal** – Operational use of launch in unmanned configuration

## ***Collaborate***

- **Activities** – SailDrone CRADA, USM and UNH partnerships
- **2019 Goal** – Integration and operation of seafloor mapping sonar on SailDrone.

